ABSTRACT OF THE DISCLOSURE

Disclosed is an optical pick-up actuator configured to achieve a multiaxial driving operation using a combination of a moving magnet system and a moving coil system. The optical pick-up actuator includes a first magnet unit, and a second magnet unit. The first magnet unit serves to conduct a tilt compensation, and the second magnet serves to conduct focusing and tracking operations. The second magnet unit for the tilt compensation is configured to conduct a tilt compensation in a tangential direction and a tilt compensation in a radial direction in an independent fashion.

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